

Randomness: A Dynamical Point of View

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(Joint work with P. Gács and M. Hoyrup)

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Introduction

Overview

Algorithmic randomness

Definitions

Computable Probability Spaces

Computability

Algorithmic Probability Theory

Dynamical Randomness

Typicalness

Typicalness vs Algorithmic Randomness

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Randomness

Ingredients:

- 1 a physical process
- 2 its observation (measurements)

Randomness \sim unpredictability

Mathematical Models:

- 1 Probability Theory
- 2 Algorithmic Randomness (Probability + Computability)
- 3 Ergodic Theory (Dynamical Systems + Probability)

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- Dynamical Randomness (Ergodic Theory + Computability):
 - To follow the typical statistical behavior of all the “effective” processes.
- In this talk:
 - 1 Introduction to Computable Probability Spaces
(some new concepts: almost decidable sets, almost computable functions, isomorphisms)
 - 2 Some structural results about these spaces,
 - 3 Within this setting, comparison between algorithmic randomness and the dynamical notion,
(Characterization of Schnorr randomness in terms of its dynamical properties)

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Martin-Löf

Definition (Martin-Löf, 1966)

A sequence of sets $(U_n)_{n \in \mathbb{N}}$ is a **μ -Martin-Löf test** if:

- U_n is a constructive open set (uniformly)
- $\mu(U_n)$ decays to zero at a computable rate.

any subset of $\bigcap_n U_n$ is called a **μ -effective null set**.

Definition (Martin-Löf, 1966)

x is **μ -Martin-Löf random** if it lies in no effective null set.

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More random objects

Some generalizations of random objects

- 1 Random closed sets (Cenzer),
- 2 Random brownian motion: $(\mathcal{C}_0([0, 1]), W)$, with W the Wiener measure (Fouché),
- 3 Abstract probability space (X, μ) (Gács).

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Computable metric spaces

We work on:

- computable metric spaces

(A metric space (X, d) + countable dense subset S s.t. $d|_S$ is computable).

Examples

- 1 Euclidean spaces \mathbb{R}^n ,
- 2 Cantor space $\{0, 1\}^{\mathbb{N}}$,
- 3 Continuous functions $\mathcal{C}([0, 1])$,
- 4 Compact sets $\mathcal{K}(\mathbb{R}^n)$,
- 5 *Probability measures over a computable metric space $\mathcal{M}(X)$*

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Computable metric spaces

An important example

Let (X, d) be a metric space. Let $\mathcal{M}(X)$ be the set of probability measures on X .

- 1 $\mathcal{M}(X)$ has a “natural” topology, the **weak topology**:

$$\mu_n \rightarrow \mu \text{ iff } \int f \, d\mu_n \rightarrow \int f \, d\mu \text{ for all } f \in C_b(X).$$

- 2 $\mathcal{M}(X)$ has a metric, the **Prokhorov metric** π , which induces the weak topology.
- 3 if (X, d, S) is a computable metric space, then $(\mathcal{M}(X), \pi, \mathcal{N})$ is a computable metric space.

$\mathcal{N} = \{\nu_0, \nu_1, \dots\}$: measures concentrated on finite subsets of S .

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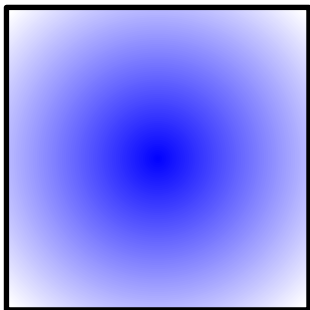
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Computable probability measure

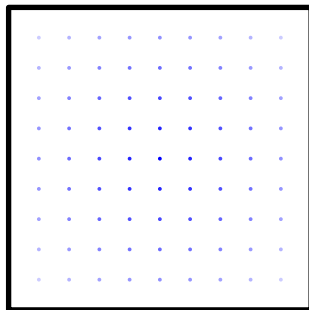
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A probability measure μ is **computable** if it is a computable point of $(\mathcal{M}(X), \pi, \mathcal{N})$.

i.e. there is a computable sequence $\nu_n \in \mathcal{N}$ satisfying $\pi(\nu_n, \mu) < 2^{-n}$.



A measure μ



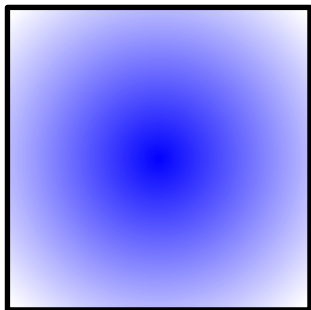
An approximation ν_3 of μ

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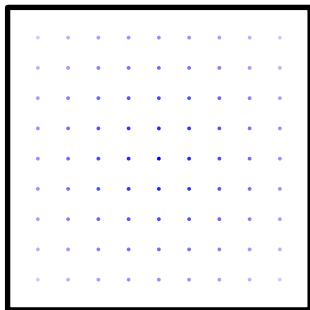
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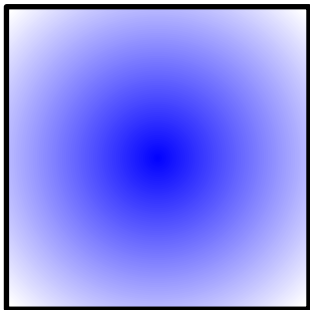
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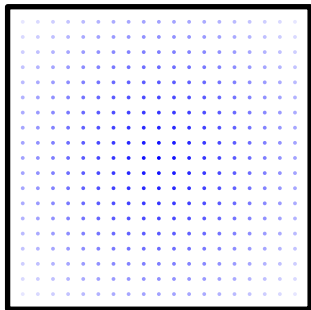
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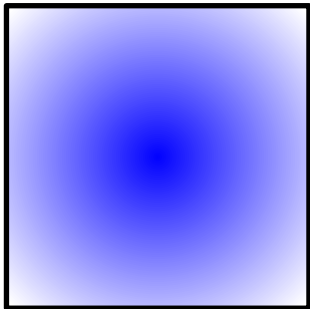
An approximation ν_6 of μ

Computable probability measure

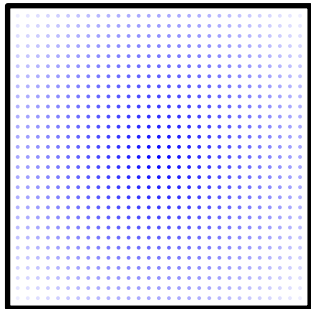
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A measure μ



An approximation ν_8 of μ

Computable probability measure

Let $A \subset X$ be open. In general, the function $\mu \rightarrow \mu(A)$ is not computable.

Example

For $X = \mathbb{R}$ and $A = (0, 1)$ we have:

- $\delta_{\frac{1}{n}} \rightarrow \delta_0$ (weakly), and
- $\delta_{\frac{1}{n}}(A) = 1$ for all n but $\delta_0(A) = 0$.

So $\mu \rightarrow \mu(A)$ is not computable since it is even not continuous.

Theorem (Hoyrup and R.)

Let $\mu \in \mathcal{M}(X)$. The following are equivalent:

- μ is computable
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We work on:

- computable metric spaces
- and with computable probability measures.

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Algorithmic probability theory

Definition

- $f : X \rightarrow Y$ is **almost computable** if it is computable on a constructive G_δ -set of measure one.
- A set $A \subset X$ is **almost decidable** if its indicator function 1_A is almost computable.
- An **effective morphism** $f : (X, \mu) \rightarrow (Y, \nu)$ is an almost computable function $f : X \rightarrow Y$ which maps μ to ν .

Spaces which are **effectively isomorphic** are then naturally defined.

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Let (X, μ) be any computable probability space.

Theorem (Hoyrup and R.)

- ① *Almost decidable sets form a **generating constructive algebra**:*
 - *unions and intersections are **computable operations**,*
 - *almost decidable sets have **computable measure**.*
- ② *(X, μ) is **effectively isomorphic** to $(\{0, 1\}^{\mathbb{N}}, \nu)$ for some **computable** ν .*
- ③ *When μ has no mass point, ν can be taken to be the **uniform measure***

Application

Transfer of algorithmic randomness.

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Algorithmic probability theory and Random points

Theorem

When restricting to random points,

	(X, μ)	\rightsquigarrow	(R_μ, μ)
<i>function</i>	<i>almost computable</i>		<i>computable</i>
<i>set</i>	<i>almost decidable</i>		<i>decidable</i>
<i>morphism</i>	<i>isomorphism</i>		<i>homeomorphism</i>

and so on...

(In particular Morphisms preserve algorithmic randomness.)

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- Thus, $\{x, T(x), T^2(x), \dots\}$ represents the **trajectory** of the system.

Ergodic theory

The study of dynamical systems from a probabilistic point of view

- **Focuses on the process (a deterministic one):**

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 1. How does randomness arise?
 - “sensitivity” (chaos) + errors in measurements.
 2. How random is a given process?
 - mixing properties
 - decay of correlations
 - entropy

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 - mixing properties
 - decay of correlations
 - entropy
- **AND on outcomes** (observations performed over time):
 3. Probabilistic laws shared by sequences of measurements?
 - Ergodic theorems,

Typical statistical behavior

Let T be an endomorphism of (X, μ) and $x \in X$.

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Theorem (Birkhoff ergodic theorem)

Let $f \in L^2$, then with probability one:

$$A_n^f(x) := \frac{f(x) + f(T(x)) + \dots + f(T^{n-1}(x))}{n} \longrightarrow \int_X f d\mu$$

Typical points

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If we replace continuous by **computable**, the above definition remains unchanged.

In the computable context, one can suppress the dependency on T .

Definition (typical points)

x is called **typical** if it is T -typical for all the **effective** endomorphisms T that are ergodic.

Effectively ergodic systems

Let us put

$$P_n^\delta(f) = \mu \left\{ x \in X : \sup_{N \geq n} |A_N^f(x) - \int f d\mu| > \delta \right\}.$$

Then the ergodic theorem is equivalent to the following assertion:

$$\lim_{n \rightarrow \infty} P_n^\delta(f) = 0 \quad \text{for all } \delta > 0.$$

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T is **effectively ergodic** if we have a computable rate here.

Definition (weakly typical points)

x is called **weakly-typical** if it is T -typical for all the **effective** endomorphisms T that are **effectively ergodic**.

Effectively ergodic systems

V'yugin exhibited a (non ergodic) system having uncomputable rate of convergence in Birkhoff theorem.

Problem

do ergodic but not effectively ergodic systems exist?

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For any pair (f, g) of integrable functions we put

$$c_n(f, g) := \left| \int f \circ T^n \cdot g \, d\mu - \int f \, d\mu \cdot \int g \, d\mu \right|.$$

T is **mixing** if the correlation coefficients c_n converge to zero.

Effectively ergodic systems

and decay of correlations

Theorem (Hoyrup and R.)

Let $s > 1$. If T is \ln^{-s} -mixing then it is effectively ergodic.

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Example

- Independent systems
- Markov systemes
- Hyperbolic systems
- Piecewise-expanding systems
- ...etc

Typicalness vs Algorithmic Randomness

Let (X, μ) be a computable probability space.

Theorem (Corollary of (V'yugin, 1998))

Martin-Löf random \implies *typical*.

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Typicalness vs Algorithmic Randomness

Theorem

Schnorr randomness

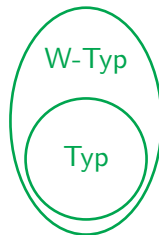
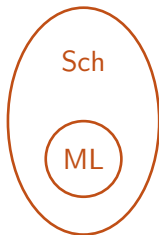
(↑)

Martin-Löf randomness

weak typicalness

(↑)

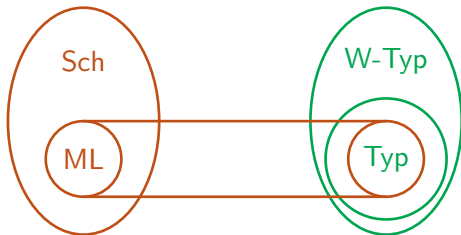
typicalness



Typicalness vs Algorithmic Randomness

Theorem

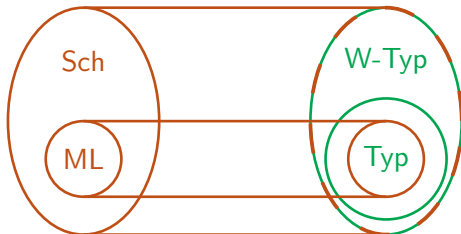
Schnorr randomness
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 (↑)
typicalness



Typicalness vs Algorithmic Randomness

Theorem

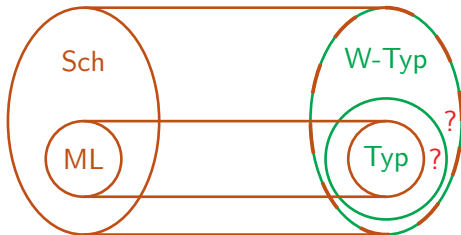
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Typicalness vs Algorithmic Randomness

Theorem

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Sketch of the proof

Schnorr random \Rightarrow Weakly typical:

Let T be effectively ergodic and f almost computable. Put

$$D_n^\delta = \left\{ x \in X : \sup_{N \geq n} \left| A_N^f(x) - \int f \, d\mu \right| > \delta \right\},$$

Show that $\exists \delta_k \rightarrow 0$ such that, for each k , no Schnorr random point belongs to

$$\bigcap_n D_n^{\delta_k}.$$

Sketch of the proof

Schnorr random \Rightarrow Weakly typical:

Since T and f are almost computable, so are the functions:

$$\bar{f}_N := \left| A_N^f(x) - \int f \, d\mu \right|,$$

then we prove the following:

Lemma

If functions $f_i : X \rightarrow \mathbb{R}$ are uniformly almost computable, then there exists a computable sequence (x_k) satisfying:

- x_k is dense,
- $\mu(\{f_i^{-1}(x_k)\}) = 0$.

Sketch of the proof

Schnorr random \Rightarrow Weakly typical:

Hence, there exists a computable sequence $\delta_k \rightarrow 0$ such that:

$$\bar{f}_N^{-1}(\delta_k, \infty) = \left\{ x \in X : \left| A_N^f(x) - \int f \, d\mu \right| > \delta_k \right\}$$

are uniformly almost decidable sets.

The construction of the required Schnorr test follows.

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Weakly typical \Rightarrow Schnorr random:

If x is not Schnorr random, we construct an effectively ergodic system T such that x is not T -typical.

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Weakly typical \Rightarrow Schnorr random:

If x is not Schnorr random, we construct an effectively ergodic system T such that x is not T -typical.

We use the following modification of a result by Schnorr:

Proposition

If the sequence $\omega \in (\{0, 1\}^{\mathbb{N}}, \text{uniform measure})$ is not Sch-random, then there exists an isomorphism φ of $(\{0, 1\}^{\mathbb{N}}, \text{uniform measure})$ such that $\varphi(\omega)$ does not satisfy the law of large numbers.

That is, the sequence $\varphi(\omega)$ is not typical for the shift transformation σ , defined by:

$$\sigma(\omega_0\omega_1\omega_2\dots) = \omega_1\omega_2\omega_3\dots$$

Sketch of the proof

Weakly typical \Rightarrow Schnorr random:

We use the **isomorphism Theorem** to transfer the dynamic on Cantor space to the general computable probability space:

If ϕ is the isomorphism between (X, μ) and $(\{0, 1\}^{\mathbb{N}}, \text{uniform measure})$ and $\psi = \phi \circ \varphi$, then

$$T := \psi^{-1} \circ \sigma \circ \psi$$

satisfy the required properties.

Remark

T has exponential decay of correlations. Hence T is effectively ergodic.

Este es el fin. Gracias.